

# **Automatic Polishing Robot Grinding Machine Flexible High Precision**

### **Basic Information**

Place of Origin: Guangdong, ChinaBrand Name: Jin Hongxiang

Certification: CE
Model Number: 1510
Minimum Order Quantity: 1 set
Price: Negotiable

Packaging Details: Export safety wooden case
 Delivery Time: 5-10 days or negotiation
 Supply Ability: 50 Set/Sets per Month



### **Product Specification**

Applicable Industries: Building Pipes, Process Products,

Automobile Sheet Metal,

• Core Components: PLC, Precision Servo, Robot Body, Welding

Power Supply, Control Cabinet

Product Name: Industrial 6 Axis Arm Welding Robot

• Key Selling Points: Flexible, Stable, Durable And High Precision

• Weight (KG): 170

Operation Type:
 Software

• Feature: Fully Automatic Arbitrary Action

Programming

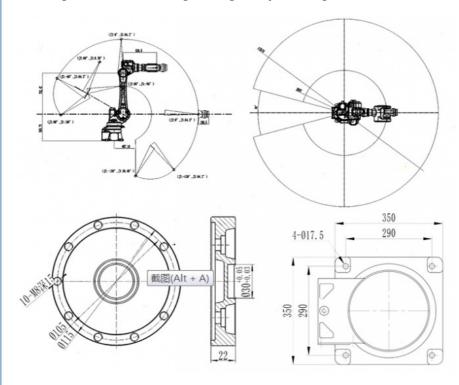
• Function: Automatic Welding

• Highlight: Automatic Robot Grinding Machine,

Flexible Robot Grinding Machine, High Precision Robot Polishing Machine

## **Product Description**

# **Grinding robot Automatic grinding and polishing**





필号	LM1850-3C-6	动作类型	多关节型	
额定负载 ( kg)	30	活动半径 (mm)	1850	
重复定位精度 ( mm )	±0.05	防护等级	防护等级 IP65	
工作范围	第一轴		±170°	
	第二轴	+120°/-63°		
	第三轴	±130°		
	第四轴	±360°		
	第五轴	+20°/-190°		
	第六轴	±360°		
最大速度	第一轴		148º/sec	
	第二轴	148°/sec		
	第三轴	148°/sec		
	第四轴	222º/sec		
	第五轴	222°/sec		
	第六轴	148°/sec		
重量 ( kg )	≈250	轴数	6	
结构形式	串联	安装方式	地面安装、支架安装、倒置安装	

Application characteristics
Keep the consistency of product processing accuracy, ensure reliable quality and reduce scrap rate;
Robots work instead of operators, and operators do not directly contact dangerous processing equipment to avoid industrial accidents;

Redevelopment, users can conduct secondary programming according to different parts, shorten the cycle of product upgrading and reduce the corresponding equipment investment.

Welding workpiece



### **ROBOT BODY TECHNICAL PARAMETERS**

Model		CRP-RH14-10-W	
Arm form		Vertical multiple joints	
Degree of freedom		6 axis	
Maximum payload		10KG	
Repeated positioning accuracy		±0.08mm	
Maximum reaching distance		1454mm	
Robot body weight		170KG	
Installation mode		Ground,upside down mounting,wall mounting	
	axis 1	Ground/upside down mounting- 167°~167°,wall mounting -30°~30°	
Maximum travel	axis 2	-155°~90°	
	axis 3	-175°~240°	
	axis 4	-190°~190°	
	axis 5	-105°~130°	
	axis 6	-105°~130°	
	axis 1	169°/s	

Maximum axis speed	axis 2	169°/s	
	axis 3	169°/s	
	axis 4	301°/S	
	axis 5	220°/s	
	axis 6	743°/S	
Allowable torque	axis 4	20N.m	
	axis 5	5 20N.m	
	axis 6	11N.m	
Allowable moment of inertia	axis 4	0.5kg.m2	
	axis 5	0.5kg.m2	
		1	

### corner of the warehouse



"Our purpose: Every device, we must do better!!

reminder:
Our products are constantly upgraded and improved.
If the color or structure changes, the actual object shall prevail"

# Dongguan Jinghongxiang Automation Equipment Co., Ltd.



13925780098



jhx16888@gmail.com

